INTERNATIONAL AUDIO LABORATORIES ERLANGEN A joint institution of Fraunhofer IIS and Universität Erlangen-Nürnberg



Tutorial 5, ISMIR Milan, November 5, 2023



Learning with Music Signals: Technology Meets Education

Audio Decomposition

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Friedrich-Alexander-Universität Erlangen-Nürnberg



Source Separation

- Decomposition of audio stream into different sound sources
- Central task in digital signal processing
- "Cocktail party effect"





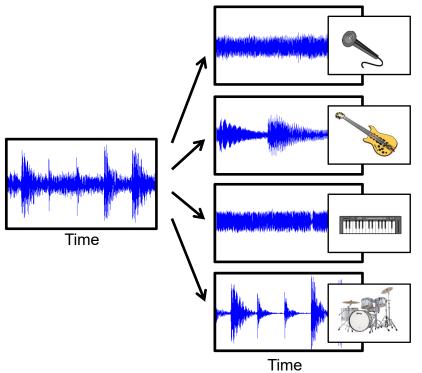
Source Separation

- Decomposition of audio stream into different sound sources
- Central task in digital signal processing
- "Cocktail party effect"
- Several input signals
- Sources are assumed to be statistically independent



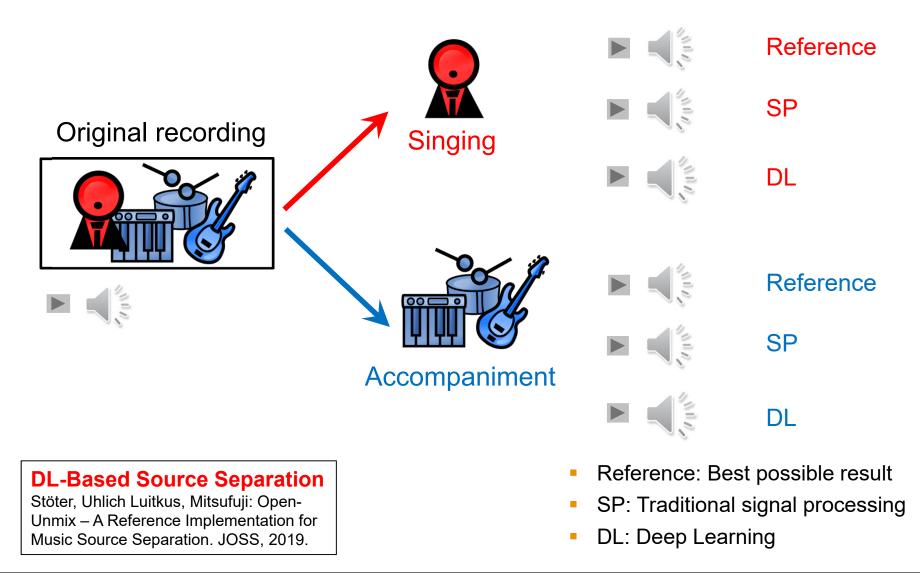
Source Separation (Music)

- Main melody, accompaniment, drum track
- Instrumental voices
- Individual note events
- Only mono or stereo
- Sources are often highly dependent





Source Separation (Singing Voice)



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Meinard Müller



Score-Informed Source Separation

Exploit musical score to support decomposition process

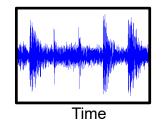
Musical Information



Ewert, Pardo, Müller, Plumbley: Score-Informed Source Separation for Musical Audio Recordings. IEEE SPM 31(3), 2014.

Audio Signal

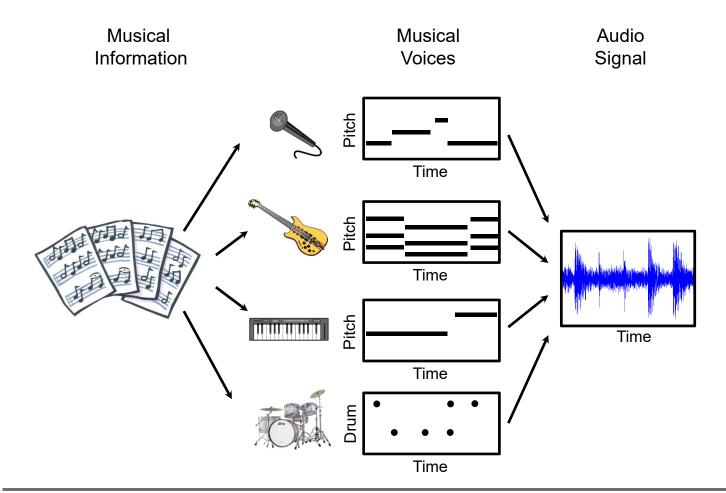






Score-Informed Source Separation

Exploit musical score to support decomposition process



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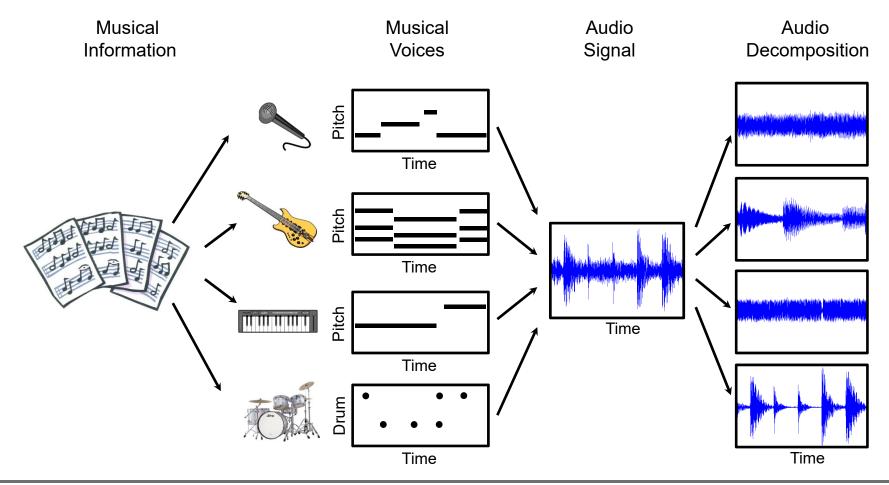


Score-Informed Source Separation

Exploit musical score to support decomposition process

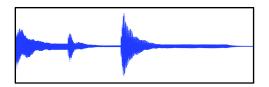
Prior Knowledge Ewert, Pardo, Müller, Plumbley:

Score-Informed Source Separation for Musical Audio Recordings. IEEE SPM 31(3), 2014.

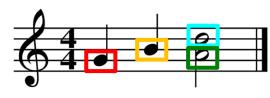


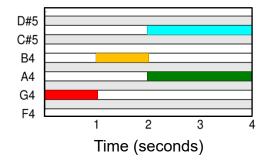


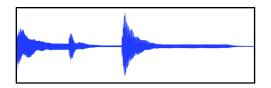




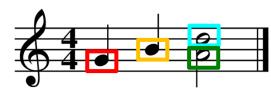


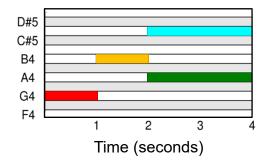


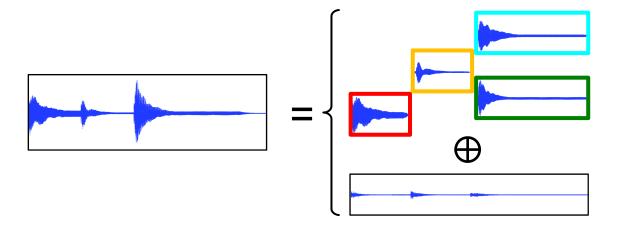




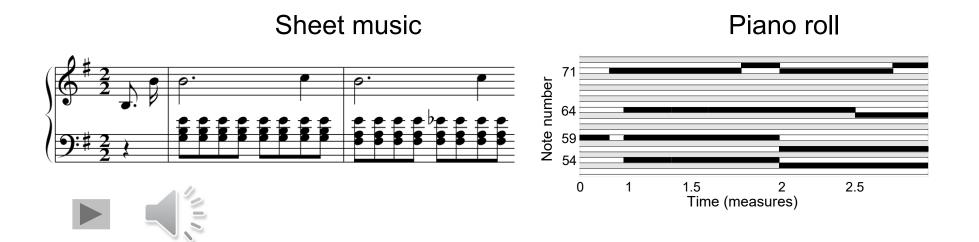




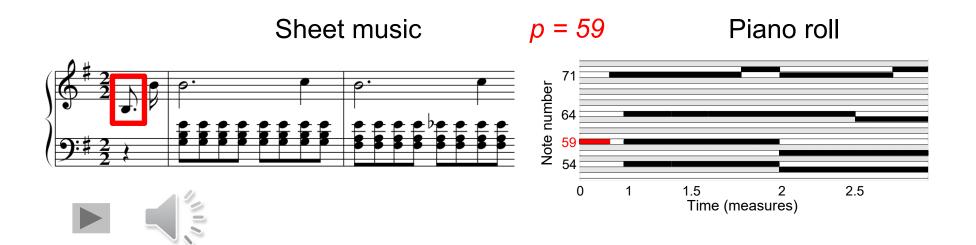




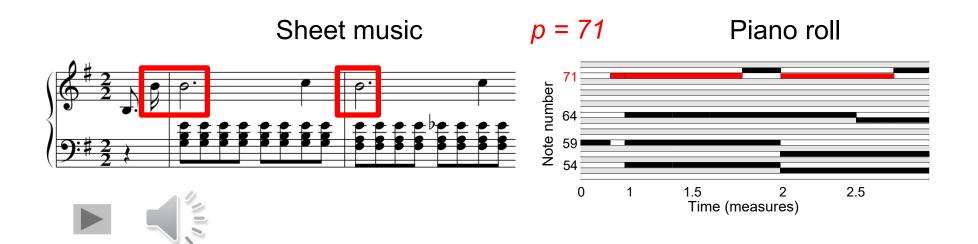




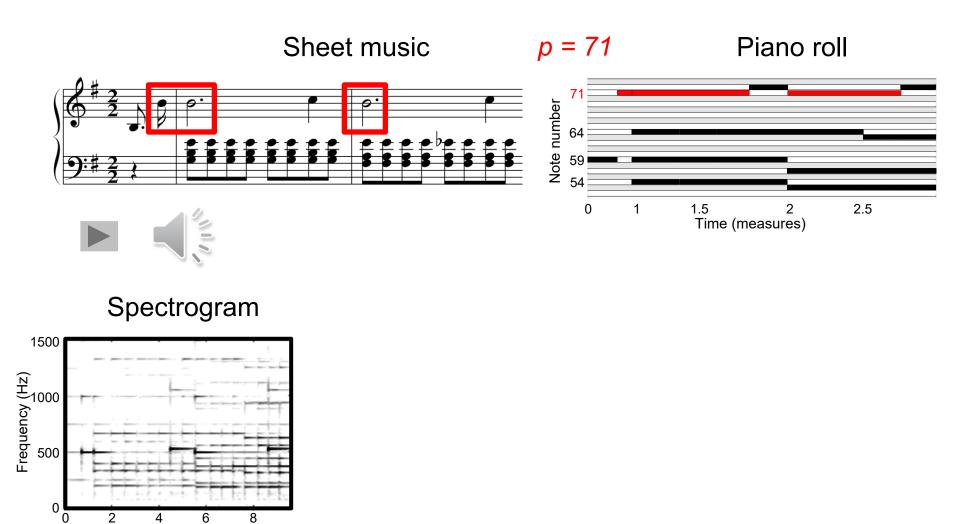






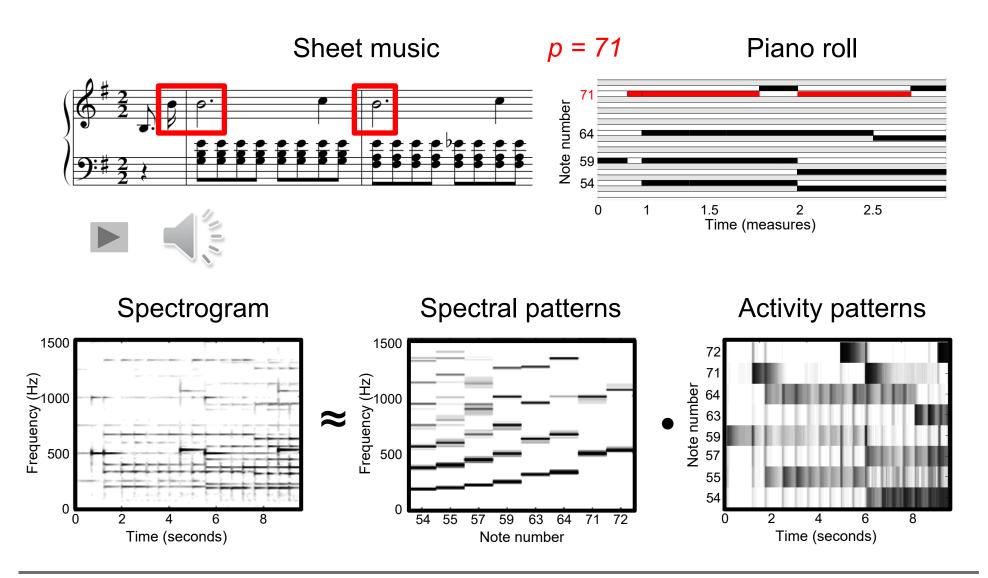






Time (seconds)

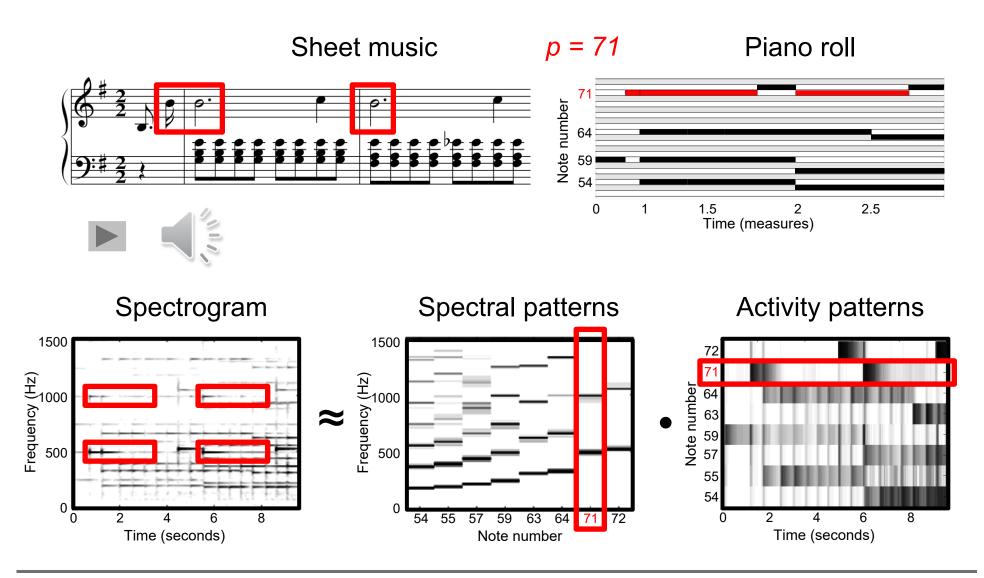




Tutorial ISMIR Learning with Music Signals AUDIO

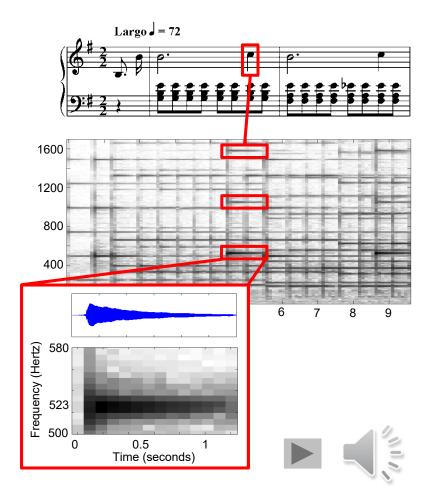
LABS

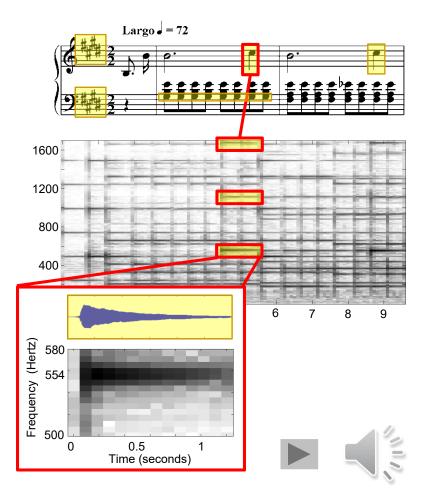
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Tutorial ISMIR Learning with Music Signals







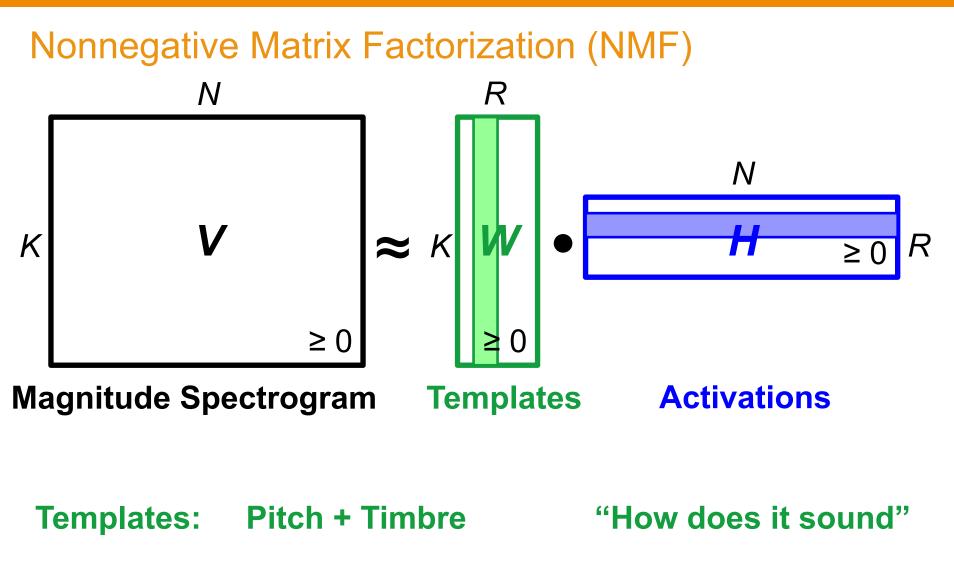
Tutorial ISMIR Learning with Music Signals



 $V \in \mathbb{R}_{\geq 0}^{K \times N} \qquad W \in \mathbb{R}_{\geq 0}^{K \times R} \qquad H \in \mathbb{R}_{\geq 0}^{R \times N}$

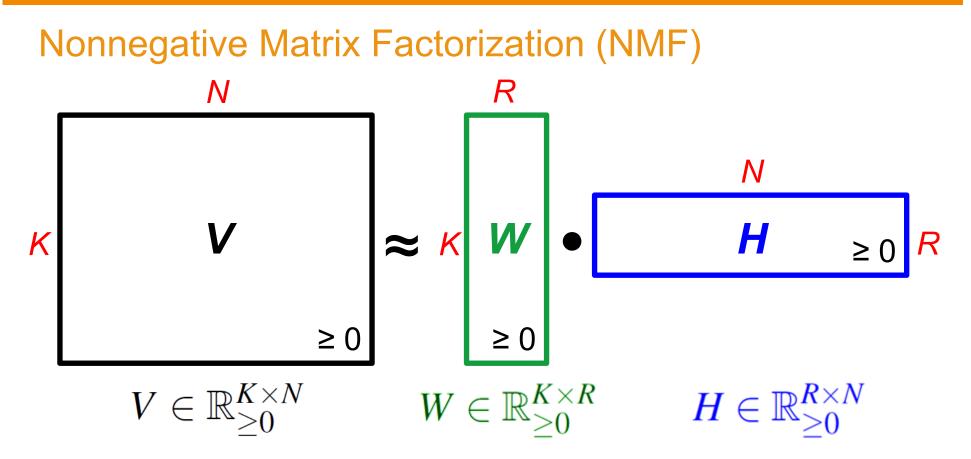


R



Activations: Onset time + Duration "When does it sound"





Dimensionality reduction

- K, N typically much larger than R (maximal rank)
- Example: N = 1000, K = 500, R = 20 K x N = 500,000, K x R = 10,000, R x N = 20,000



Nonnegative Matrix Factorization (NMF) Ν RΝ Η K ≥ 0 $V \in \mathbb{R}_{>0}^{K \times N}$ $W \in \mathbb{R}_{>0}^{K \times R}$ $H \in \mathbb{R}^{R \times N}_{>0}$

Nonnegativity:

- Prevents mutual cancellation of template vectors
- Encourages semantically meaningful decomposition



Optimization problem:

Given $V \in \mathbb{R}_{\geq 0}^{K \times N}$ and rank parameter R minimize $\|V - WH\|^2$ with respect to $W \in \mathbb{R}_{\geq 0}^{K \times R}$ and $H \in \mathbb{R}_{\geq 0}^{R \times N}$.

Optimization not easy:

- Nonnegativity constraints
- Nonconvexity when jointly optimizing W and H

Strategy: Iteratively optimize W and H via gradient descent



Computation of gradient with respect to H (fixed W)

$$D := RN$$

$$\varphi^{W} : \mathbb{R}^{D} \to \mathbb{R}$$

$$\varphi^{W}(H) := \|V - WH\|^{2}$$

Variables

 $H \in \mathbb{R}^{R imes N}$ $H_{
ho
u}$ $ho \in [1:R]$ $ho \in [1:N]$



Computation of gradient with respect to H (fixed W)

$$D := RN$$

$$\varphi^{W} : \mathbb{R}^{D} \to \mathbb{R}$$

$$\frac{\partial \varphi^{W}}{\partial H_{\rho v}} = \frac{\partial \left(\sum_{k=1}^{K} \sum_{n=1}^{N} \left(V_{kn} - \sum_{r=1}^{R} W_{kr} H_{rn} \right)^{2} \right)}{\partial H_{\rho v}}$$

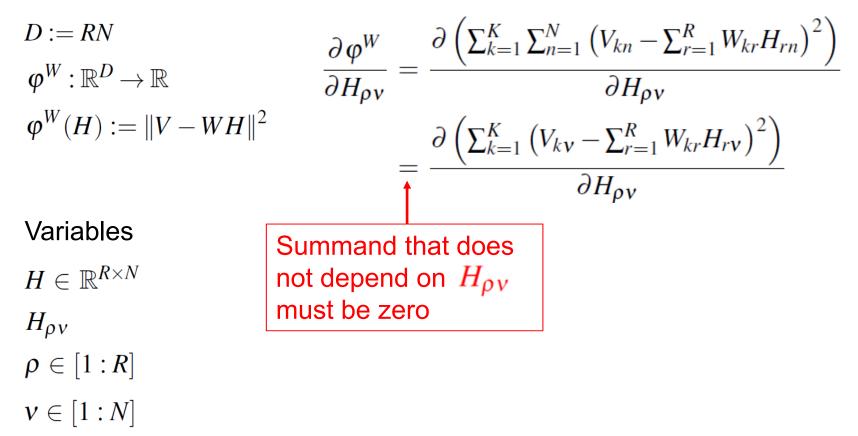
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$$\varphi^{W}(H) := \|V - WH\|^{2}$$

$$= \frac{\partial \left(\sum_{k=1}^{K} \left(V_{kv} - \sum_{r=1}^{R} W_{kr} H_{rv} \right)^{2} \right)}{\partial H_{\rho v}}$$

$$Variables$$

$$H \in \mathbb{R}^{R \times N}$$

$$H_{\rho v}$$

$$\rho \in [1:R]$$

$$v \in [1:N]$$

$$\frac{\partial \varphi^{W}}{\partial H_{\rho v}} = \frac{\partial \left(\sum_{k=1}^{K} \left(V_{kv} - \sum_{r=1}^{R} W_{kr} H_{rv} \right)^{2} \right)}{\partial H_{\rho v}}$$



Computation of gradient with respect to H (fixed W)

 $\frac{\partial \varphi^{W}}{\partial H_{\rho \nu}} = \frac{\partial \left(\sum_{k=1}^{K} \sum_{n=1}^{N} \left(V_{kn} - \sum_{r=1}^{R} W_{kr} H_{rn} \right)^{2} \right)}{\partial H_{\rho \nu}}$ D := RN $\varphi^W: \mathbb{R}^D \to \mathbb{R}$ $\boldsymbol{\varphi}^{W}(H) := \|V - WH\|^2$ $=\frac{\partial\left(\sum_{k=1}^{K}\left(V_{k\nu}-\sum_{r=1}^{R}W_{kr}H_{r\nu}\right)^{2}\right)}{\partial H_{\rho\nu}}$ $= \sum_{k=1}^{K} 2 \left(V_{k\nu} - \sum_{r=1}^{R} W_{kr} H_{r\nu} \right) \cdot \left(-W_{k\rho} \right)$ Variables $H \in \mathbb{R}^{R \times N}$ $= 2\left(\sum_{r=1}^{R}\sum_{k=1}^{K}W_{k\rho}W_{kr}H_{r\nu} - \sum_{k=1}^{K}W_{k\rho}V_{k\nu}\right)$ $H_{\rho\nu}$ $\rho \in [1:R]$ Rearrange $\mathbf{v} \in [1:N]$ summands



Computation of gradient with respect to H (fixed W)

 $\frac{\partial \varphi^{W}}{\partial H_{\rho v}} = \frac{\partial \left(\sum_{k=1}^{K} \sum_{n=1}^{N} \left(V_{kn} - \sum_{r=1}^{R} W_{kr} H_{rn} \right)^{2} \right)}{\partial H_{\rho v}}$ D := RN $\varphi^W: \mathbb{R}^D \to \mathbb{R}$ $\boldsymbol{\varphi}^{W}(H) := \|V - WH\|^2$ $=\frac{\partial\left(\sum_{k=1}^{K}\left(V_{k\nu}-\sum_{r=1}^{R}W_{kr}H_{r\nu}\right)^{2}\right)}{\partial H_{\rho\nu}}$ $= \sum_{k=1}^{K} 2 \left(V_{k\nu} - \sum_{r=1}^{R} W_{kr} H_{r\nu} \right) \cdot \left(-W_{k\rho} \right)$ Variables $H \in \mathbb{R}^{R \times N}$ $= 2\left(\sum_{r=1}^{R}\sum_{k=1}^{K}W_{k\rho}W_{kr}H_{r\nu} - \sum_{k=1}^{K}W_{k\rho}V_{k\nu}\right)$ $H_{\rho\nu}$ $\rho \in [1:R]$ $= 2 \left(\sum_{r=1}^{R} \left(\sum_{k=1}^{K} W_{\rho k}^{\top} W_{kr} \right) H_{r\nu} - \sum_{k=1}^{K} W_{\rho k}^{\top} V_{k\nu} \right)$ $\mathbf{v} \in [1:N]$ Introduce transposed W^+



Computation of gradient with respect to H (fixed W)

 $\frac{\partial \varphi^{W}}{\partial H_{\rho v}} = \frac{\partial \left(\sum_{k=1}^{K} \sum_{n=1}^{N} \left(V_{kn} - \sum_{r=1}^{R} W_{kr} H_{rn} \right)^{2} \right)}{\partial H_{\rho v}}$ D := RN $\varphi^W: \mathbb{R}^D \to \mathbb{R}$ $\boldsymbol{\varphi}^{W}(H) := \|V - WH\|^2$ $=\frac{\partial\left(\sum_{k=1}^{K}\left(V_{k\nu}-\sum_{r=1}^{R}W_{kr}H_{r\nu}\right)^{2}\right)}{\partial H_{\rho\nu}}$ $= \sum_{k=1}^{K} 2 \left(V_{k\nu} - \sum_{r=1}^{R} W_{kr} H_{r\nu} \right) \cdot \left(-W_{k\rho} \right)$ Variables $H \in \mathbb{R}^{R \times N}$ $= 2\left(\sum_{r=1}^{R}\sum_{k=1}^{K}W_{k\rho}W_{kr}H_{r\nu} - \sum_{k=1}^{K}W_{k\rho}V_{k\nu}\right)$ $H_{\rho\nu}$ $\rho \in [1:R]$ $= 2 \left(\sum_{r=1}^{R} \left(\sum_{k=1}^{K} W_{\rho k}^{\top} W_{kr} \right) H_{r\nu} - \sum_{k=1}^{K} W_{\rho k}^{\top} V_{k\nu} \right)$ $\mathbf{v} \in [1:N]$ $= 2((W^{\top}WH)_{\rho\nu} - (W^{\top}V)_{\rho\nu}).$



NMF Optimization Gradient descent

Initialization $H^{(0)} \in \mathbb{R}^{R \times N}$ Iteration for $\ell = 0, 1, 2, ...$

$$H_{rn}^{(\ell+1)} = H_{rn}^{(\ell)} - \gamma_{rn}^{(\ell)} \cdot \left(\left(W^{\top} W H^{(\ell)} \right)_{rn} - \left(W^{\top} V \right)_{rn} \right)$$

with suitable learning rate $\gamma_{rn}^{(\ell)} \ge 0$



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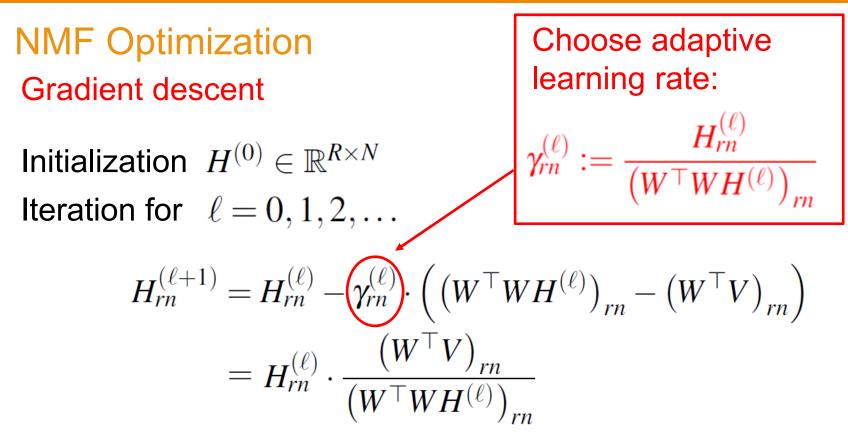
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with suitable learning rate $\gamma_{rn}^{(\ell)} \ge 0$

Issues:

- How to do the initialization?
- How to choose the learning rate?
- How to ensure nonnegativity?

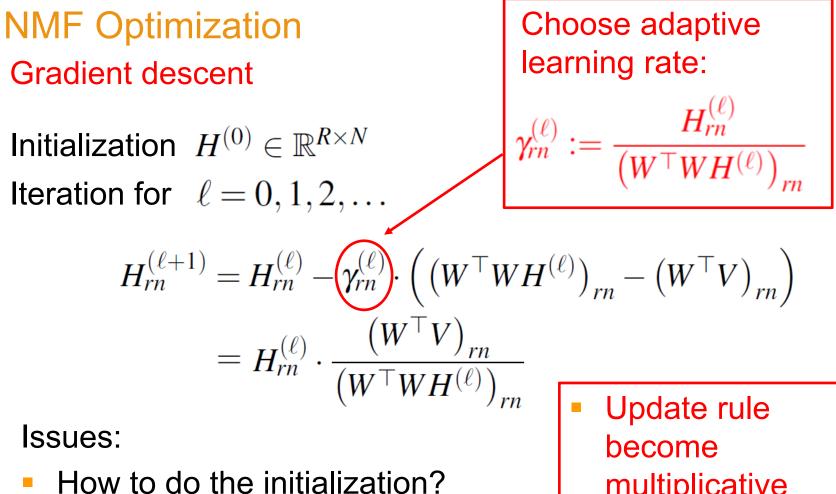




Issues:

- How to do the initialization?
- How to choose the learning rate?
- How to ensure nonnegativity?





- How to choose the learning rate?
- How to ensure nonnegativity?

- multiplicative
- Nonnegative values stay nonnegative



NMF Algorithm

Lee, Seung: Algorithms for Non-Negative Matrix Factorization. Proc. NIPS, 2000.

Algorithm: NMF ($V \approx WH$)

- Input:Nonnegative matrix V of size $K \times N$
Rank parameter $R \in \mathbb{N}$
Threshold ε used as stop criterionOutput:Nonnegative template matrix W of size $K \times R$
 - Nonnegative activation matrix *H* of size $R \times N$

Procedure: Define nonnegative matrices $W^{(0)}$ and $H^{(0)}$ by some random or informed initialization. Furthermore set $\ell = 0$. Apply the following update rules (written in matrix notation):

$$(1) \quad H^{(\ell+1)} = H^{(\ell)} \odot \left(((W^{(\ell)})^\top V) \oslash ((W^{(\ell)})^\top W^{(\ell)} H^{(\ell)}) \right)$$

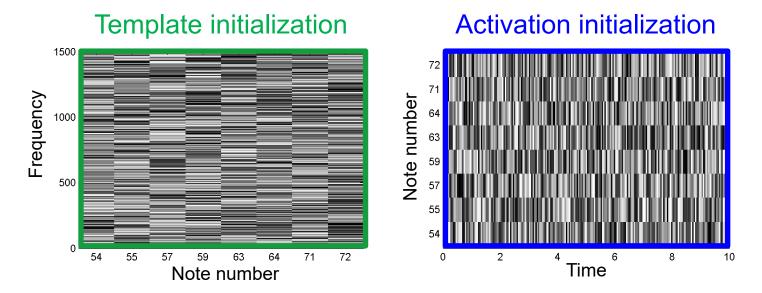
(2)
$$W^{(\ell+1)} = W^{(\ell)} \odot \left((V(H^{(\ell+1)})^{\top}) \oslash (W^{(\ell)}H^{(\ell+1)}(H^{(\ell+1)})^{\top}) \right)$$

(3) Increase ℓ by one.

Repeat the steps (1) to (3) until $||H^{(\ell)} - H^{(\ell-1)}|| \le \varepsilon$ and $||W^{(\ell)} - W^{(\ell-1)}|| \le \varepsilon$ (or until some other stop criterion is fulfilled). Finally, set $H = H^{(\ell)}$ and $W = W^{(\ell)}$.



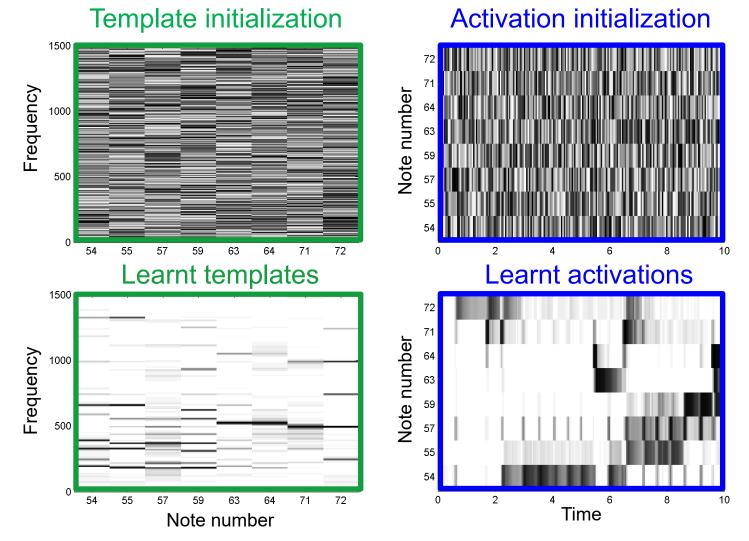
NMF-based Spectrogram Decomposition



Random initialization



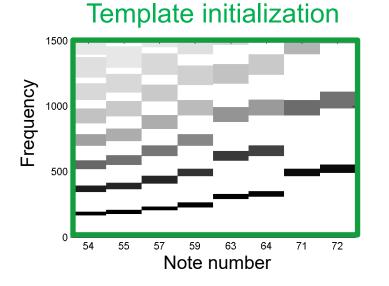
NMF-based Spectrogram Decomposition



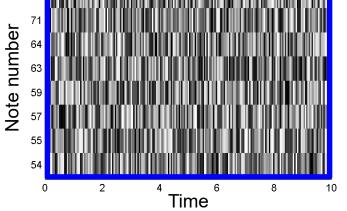
Random initialization \rightarrow No semantic meaning

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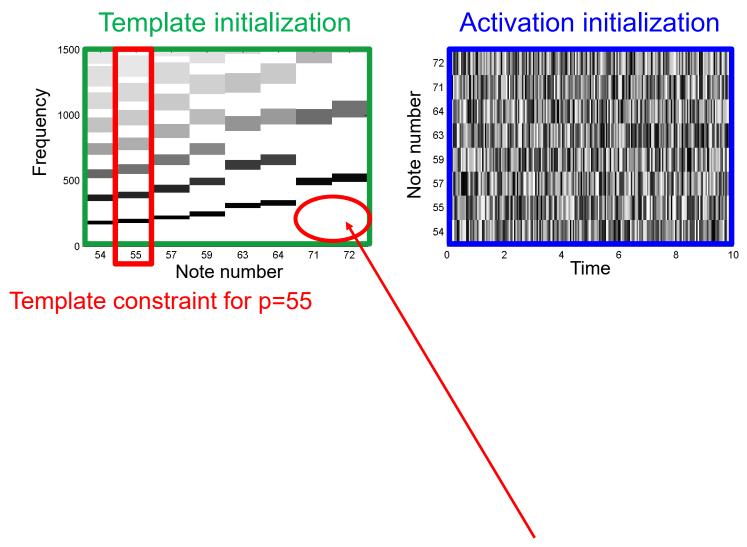
Activation initialization



Enforce harmonic structure with zero-valued entries

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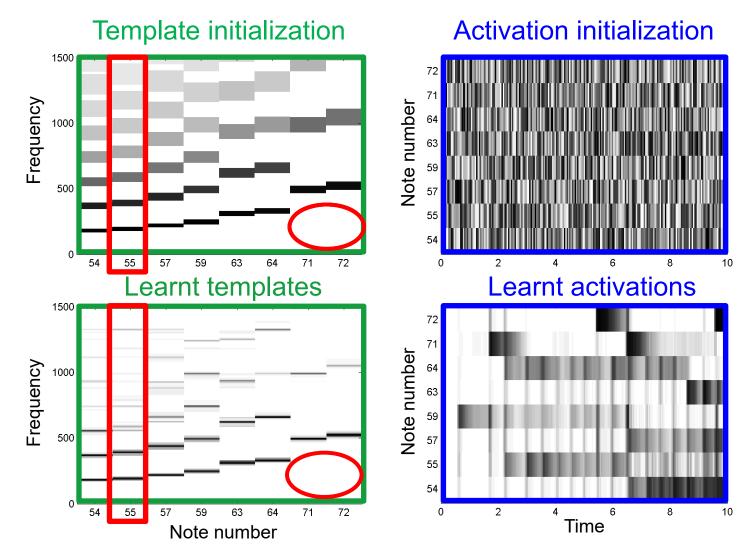




Enforce harmonic structure with zero-valued entries

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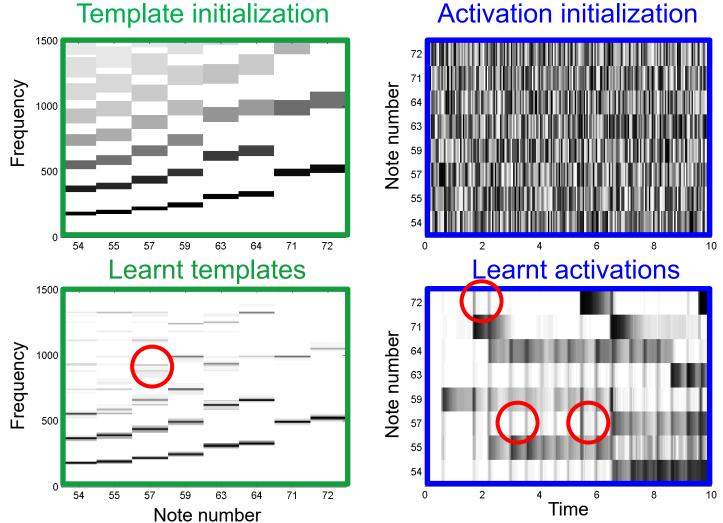




Zero-valued entries remain zero-valued entries!

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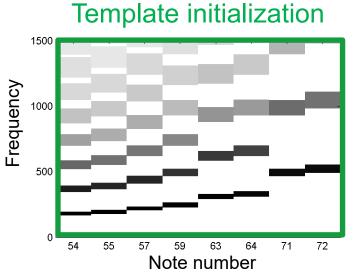




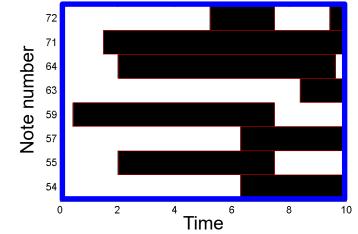
Pitch templates misused to represent onsets

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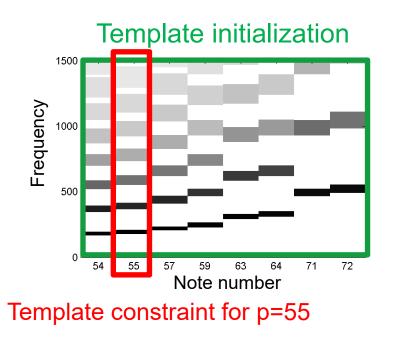




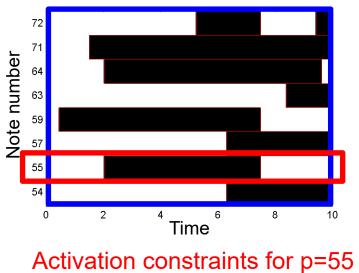
Activation initialization







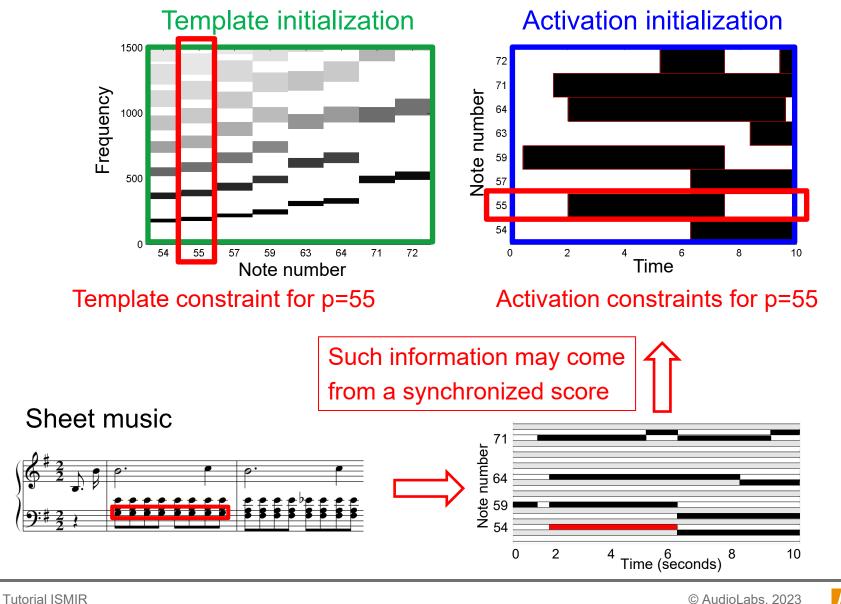
Activation initialization



AUDIO

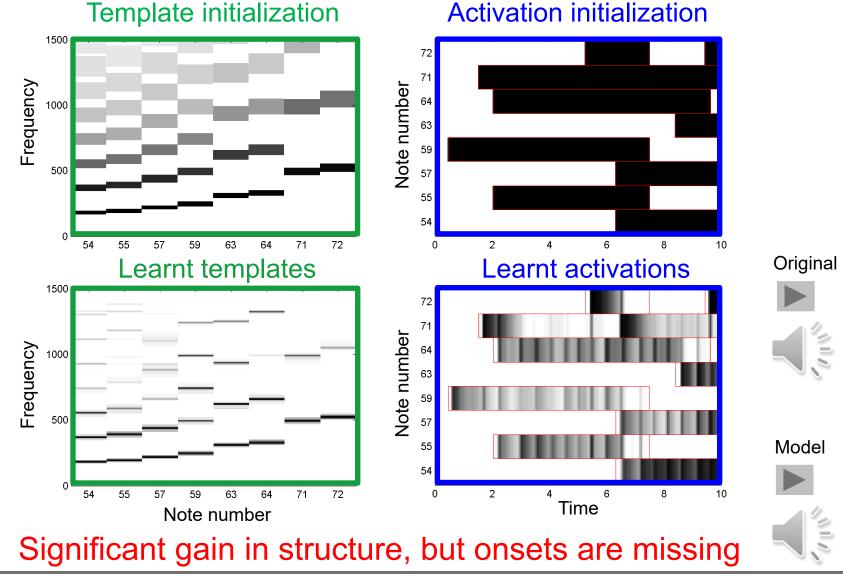
LABS





Learning with Music Signals



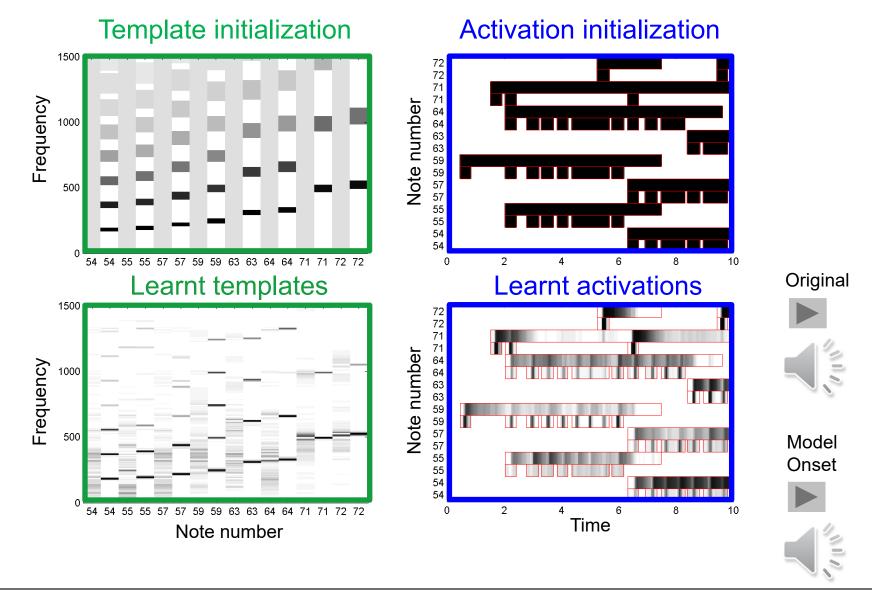


Activation initialization

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Constrained NMF: Onset Templates



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Learning with Music Signals

AUDIO

B

LA

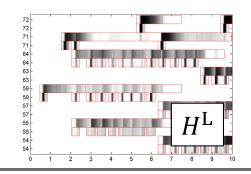
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Application: Separating left and right hands for piano



1. Split activation matrix



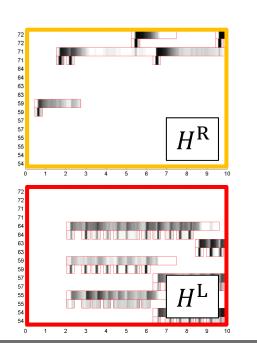




Application: Separating left and right hands for piano

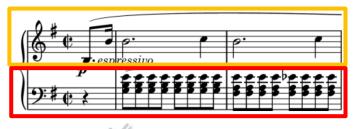


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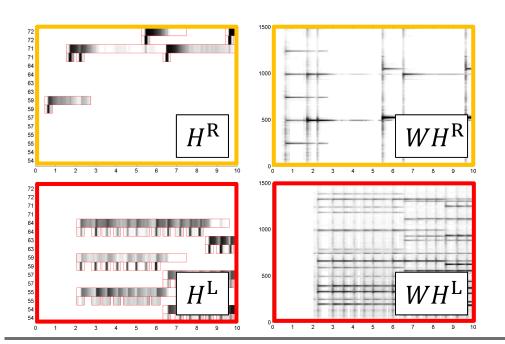




Application: Separating left and right hands for piano



- 1. Split activation matrix
- 2. Model spectrogram for left/right



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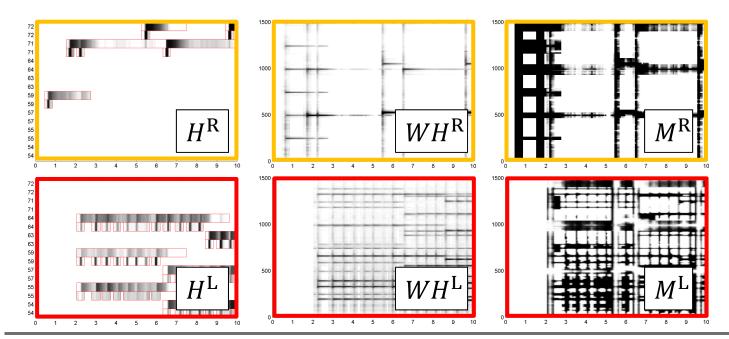


Application: Separating left and right hands for piano





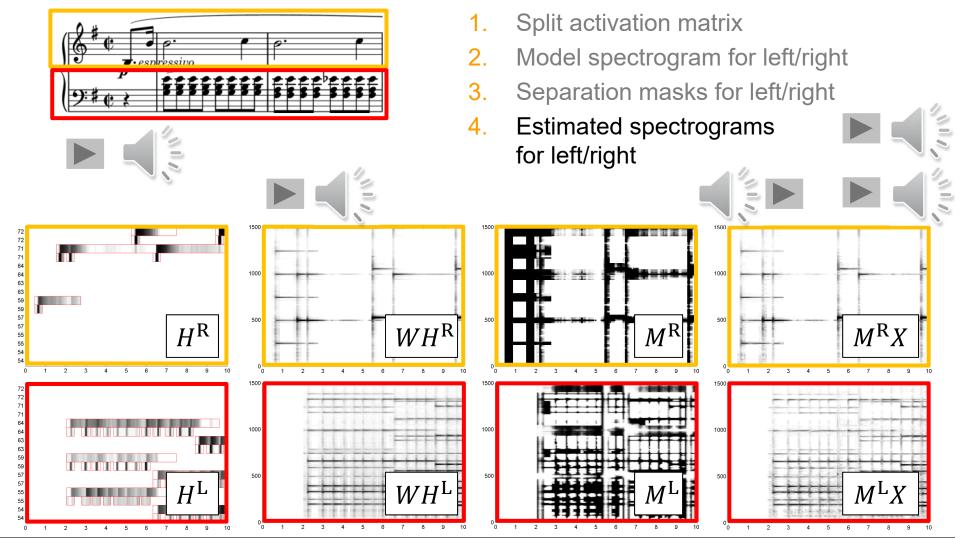
- 1. Split activation matrix
- 2. Model spectrogram for left/right
- 3. Separation masks for left/right



Tutorial ISMIR Learning with Music Signals



Application: Separating left and right hands for piano



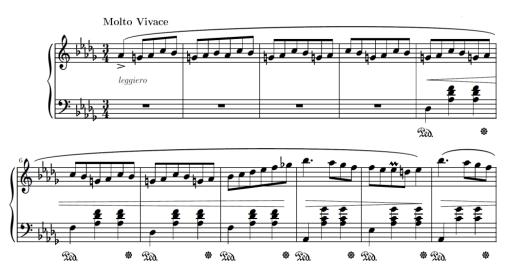
Tutorial ISMIR Learning with Music Signals AUDIO

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Meinard Müller

Application: Separating left and right hands for piano

Chopin, Waltz Op. 64, No. 1



Original



Score-Informed Constraints

Ewert, Müller: Using Score-Informed Constraints for NMF-based Source Separation. Proc. ICASSP, 2012.

Further results available at http://www.mpi-inf.mpg.de/resources/MIR/ICASSP2012-ScoreInformedNMF/



Application: Separating left and right hands for piano

Chopin, Waltz Op. 64, No. 1





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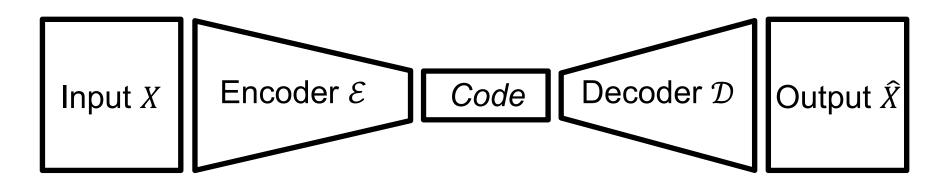


Conclusions (NMF)

- NMF used for spectrogram decomposition
- Multiplicative update rules make it easy to constrain NMF model via zero initialization
- Exploiting score information to guide separation process (requires score–audio synchronization)
- Application: Separation of arbitrary note groups from given audio recording



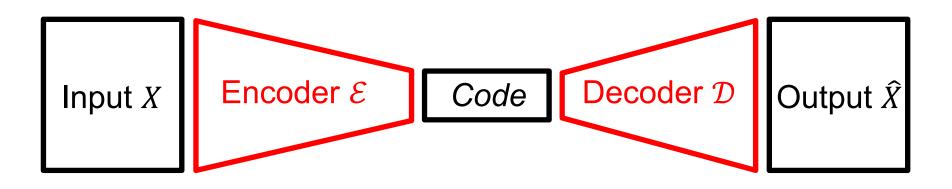
Autoencoder



- Specific type of neural network
- Encoder: Compress input X into a low-dimensional code
- Decoder: Reconstruct output \hat{X} from code



Autoencoder



- Specific type of neural network
- Encoder: Compress input X into a low-dimensional code
- Decoder: Reconstruct output \hat{X} from code
- Goal: Learn parameters for encoder and decoder such that output is close to input with respect to some loss function:

$$\mathcal{L}(X, \hat{X}) \approx 0$$

Tutorial ISMIR Learning with Music Signals



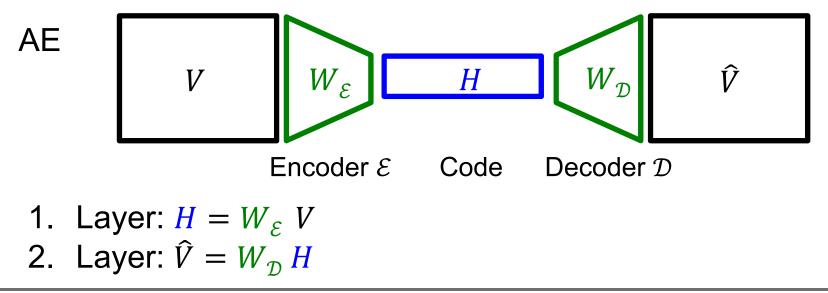
NMF and Autoencoder (AE)Nonnegative Autoencoder
Smaragdis, Venkataramani: A Neural
Network Alternative to Non-Negative
Audio Models, Proc. ICASSP 2017.NMF
$$V$$
 \thickapprox W H $=$ \hat{V}

 $V \approx WH$ implies $W^+V \approx H$ with pseudoinverse W^+

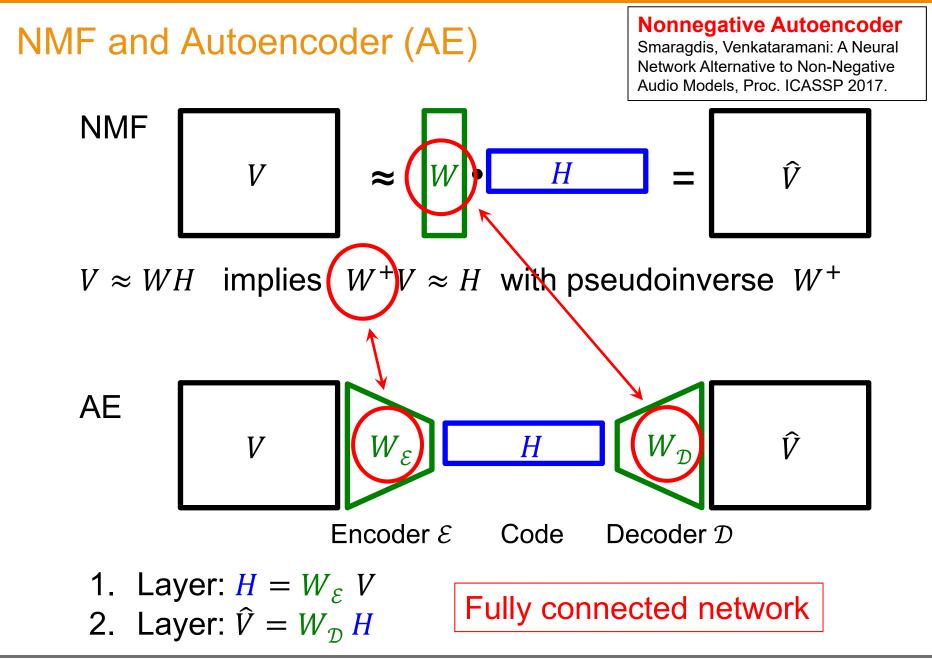


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 $V \approx WH$ implies $W^+V \approx H$ with pseudoinverse W^+



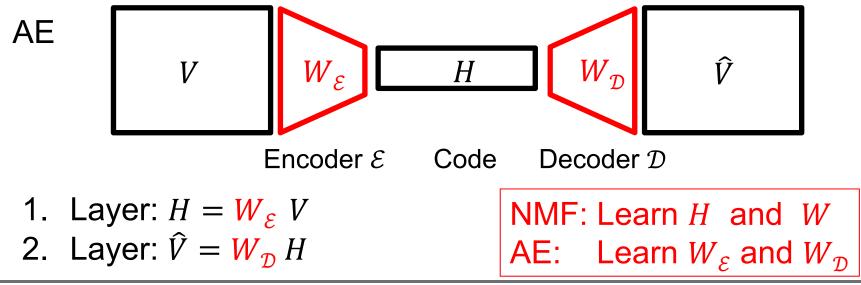






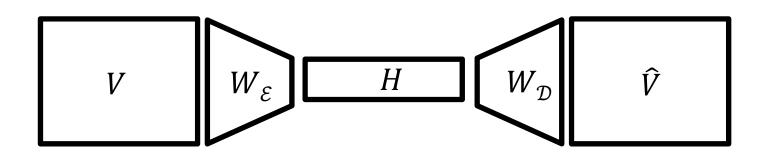
NMF and Autoencoder (AE)Nonnegative Autoencoder
Smaragdis, Venkataramani: A Neural
Network Alternative to Non-Negative
Audio Models, Proc. ICASSP 2017.NMF
$$V$$
 \thickapprox W H $=$ \hat{V}

 $V \approx WH$ implies $W^+V \approx H$ with pseudoinverse W^+



Tutorial ISMIR Learning with Music Signals

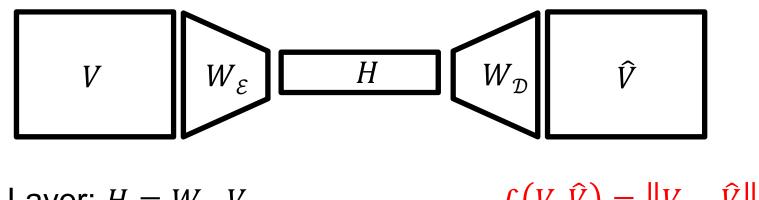




1. Layer: $H = W_{\mathcal{E}} V$ 2. Layer: $\hat{V} = W_{\mathcal{D}} H$

- How can one adjust the AE to simulate NMF?
- How can one achieve nonnegativity?
- How can one incorporate musical knowledge?





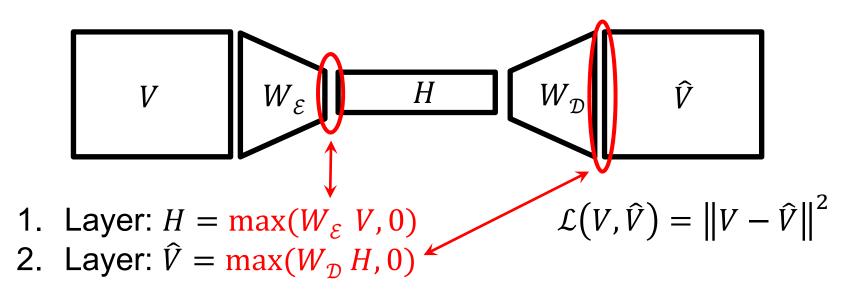
1. Layer:
$$H = W_{\mathcal{E}} V$$

2. Layer: $\hat{V} = W_{\mathcal{D}} H$

 $\mathcal{L}(V,\widehat{V}) = \left\|V - \widehat{V}\right\|^2$

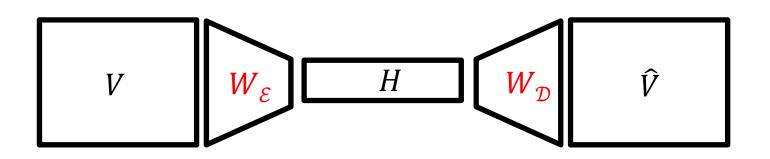
Loss function: same as in NMF





- Loss function: same as in NMF
- Activation function (ReLU) makes H and \hat{V} nonnegative



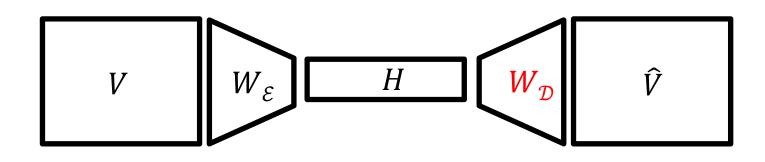


1. Layer: $H = \max(W_{\mathcal{E}} V, 0)$ $\mathcal{L}(V, \hat{V}) = \|V - \hat{V}\|^2$ 2. Layer: $\hat{V} = \max(W_{\mathcal{D}} H, 0)$ $W_{\mathcal{D}} \leftarrow \max\left(W_{\mathcal{D}} - \gamma \frac{\partial \mathcal{L}}{\partial W_{\mathcal{D}}}, 0\right)$

- Loss function: same as in NMF
- Activation function (ReLU) makes H and \hat{V} nonnegative
- Projected gradient descent can be used to keep $W_{\mathcal{D}}$ (and $W_{\mathcal{E}}$) nonnegative



Musical Constraints

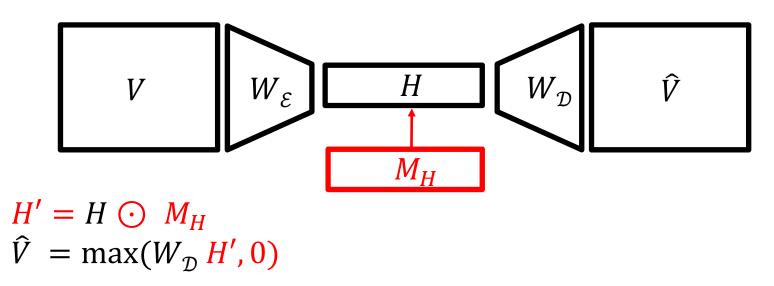


- $H = \max(W_{\mathcal{E}} \ V, 0)$ $\hat{V} = \max(W_{\mathcal{D}} \ H, 0)$
- Template constraints: Project certain entries in $W_{\mathcal{D}}$ to zero values (using projected gradient decent)



Musical Constraints

Ewert, Sandler: Structured Dropout for Weak Label and Multi-Instance Learning and Its Application to Score-Informed Source Separation. Proc. ICASSP, 2017.



- Template constraints: Project certain entries in $W_{\mathcal{D}}$ to zero values (using projected gradient decent)
- Activation constraints: Use structured dropout by applying pointwise multiplication with binary mask M_H



NAE with Multiplicative Update Rules

- Multiplicative update rules in NMF:
 - Preserve nonnegativity
 - Lead to fast convergence
- Question: Can one introduce multiplicative update rules to train network weights for NAE?
- Use in additive gradient descent

$$W^{(\ell+1)} = W^{(\ell)} - \gamma \cdot \frac{\partial \mathcal{L}}{\partial W}$$

a suitable (adaptive) learning rate γ .



NAE with Multiplicative Update Rules

Encoder:

$$H = W_{\mathcal{E}}V$$

Structured Dropout:

 $H' = H \odot M_H$

• Decoder: $\hat{V} = W_{\mathcal{D}}H'$

NMF vs. NAE



NAE with Multiplicative Update Rules

Encoder:

Decoder:

$$H = W_{\mathcal{E}}V$$

$$W_{\mathcal{E},rk}^{(\ell+1)} = W_{\mathcal{E},rk}^{(\ell)} \cdot \frac{\left(\left(\left(W_{\mathcal{D}}^{\top}V\right) \odot M_{H}\right)V^{\top}\right)_{rk}}{\left(\left(\left(\left(W_{\mathcal{D}}^{\top}W_{\mathcal{D}}H'^{(\ell)}\right) \odot M_{H}\right)V^{\top}\right)_{rk}\right)_{rk}}$$

• Structured Dropout: $H' = H \odot M_H$

 $\hat{V} = W_{\mathcal{D}}H'$

$$W_{\mathcal{D},kr}^{(\ell+1)} = W_{\mathcal{D},kr}^{(\ell)} \cdot \frac{\left(VH'^{\top}\right)_{kr}}{\left(W_{\mathcal{D}}^{(\ell)}H'H'^{\top}\right)_{kr}}$$

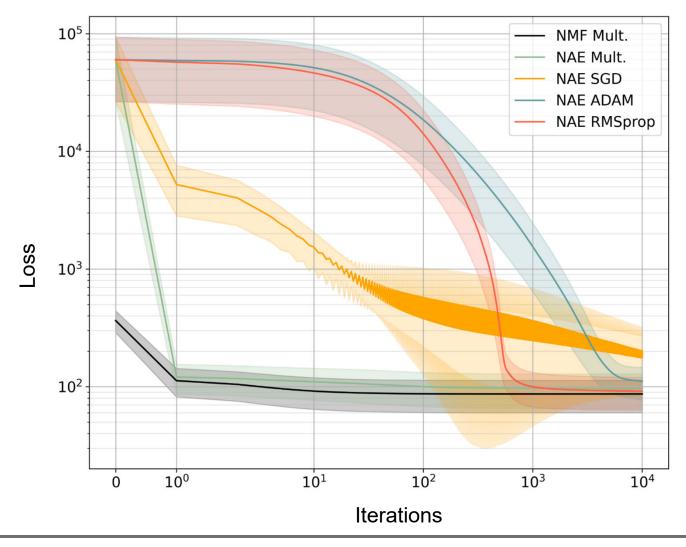
Similar idea and computation as for NMF.

NMF vs. NAE



Approximation Loss

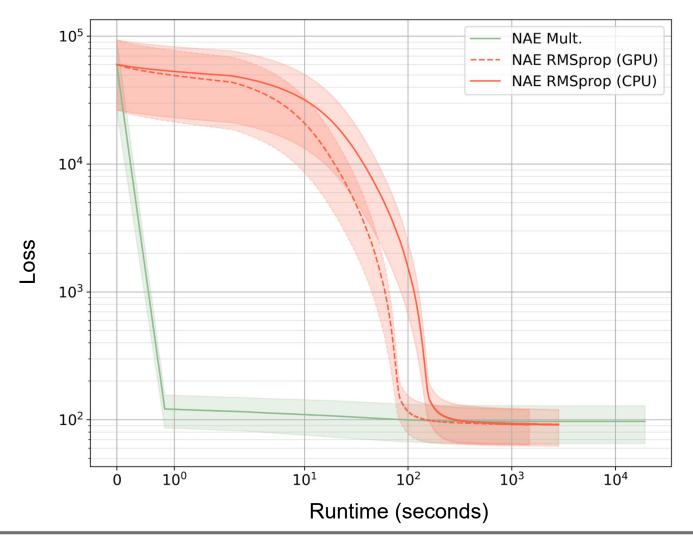
NMF vs. NAE





Approximation Loss

NMF vs. NAE





Conclusions (NAE)

- Simulation of NMF:
 - Decoder corresponds to NMF templates
 - Encoder learns a kind of pseudo-inverse
 - Code corresponds to NMF activations
- Nonnegativity can be achieved via
 - activation function (ReLU)
 - projected gradient descent
 - multiplicative update rules
- Musical knowledge can be integrated via
 - removing network weights (template constraints)
 - structured dropout (activation constraints)

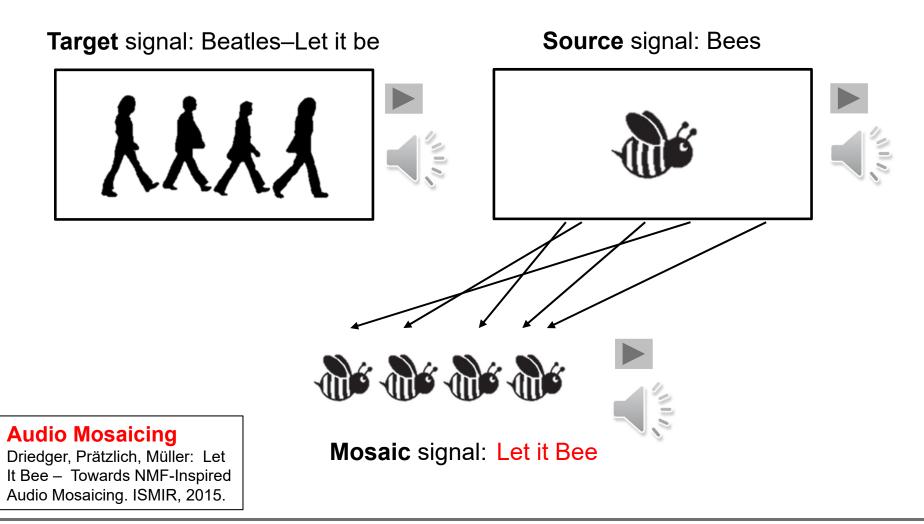


Outlook

- More complex networks
 - Deeper networks (more layers)
 - Different layer types (CNN, RNN, ...) and activation functions
 - Modification of loss function and regularization terms
- Understanding encoder decoder relationship
 - Nonnegativity
 - Pseudo-inverse
- Update rules
 - Constraints and convergence issues
 - Adaptive learning rates and projected gradient descent

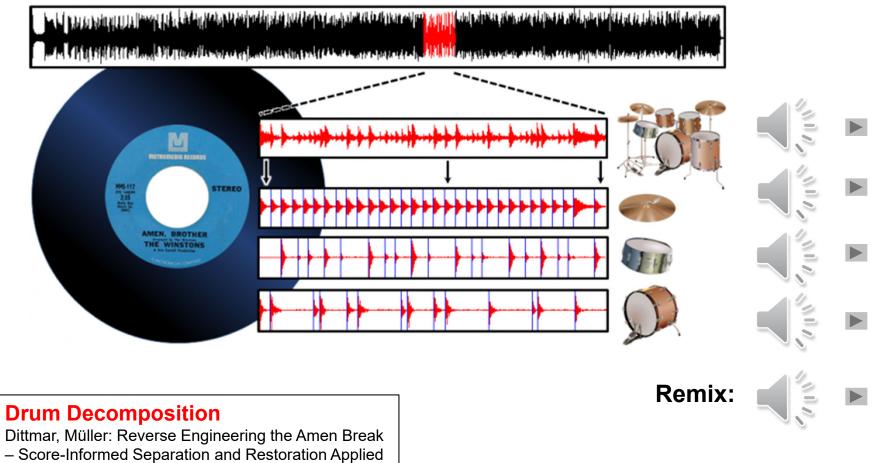


Audio mosaicing (style transfer)





Informed Drum-Sound Decomposition



to Drum Recordings. IEEE/ACM TASLP 24(9), 2016.



Major challenge: Reconstructed sound events often have artifacts

Approaches:

- Resynthesize certain sound components
- Differentiable Digital Signal Processing (DDSP) combines classical DSP and deep learning
- Generative adversarial networks may help to reduce the artifacts

DDSP

Engel et al.: DDSP: Differentiable Digital Signal Processing. ICLR, 2020.

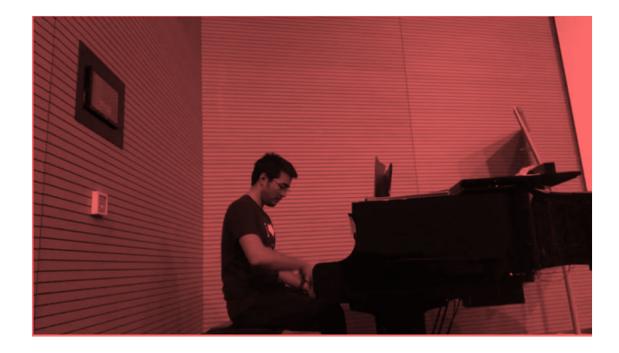


- Yigitcan Özer
- PhD student in engineering
- Pianist





- Yigitcan Özer
- PhD student in engineering
- Pianist



Only Piano!

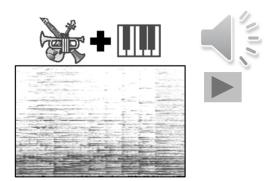


Where is the orchestra?

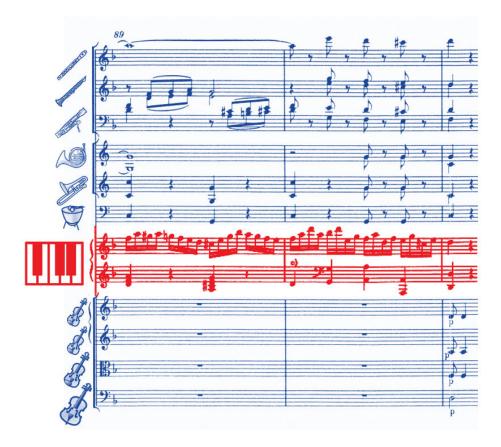


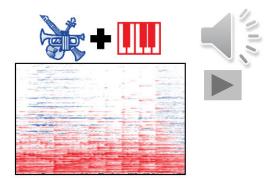




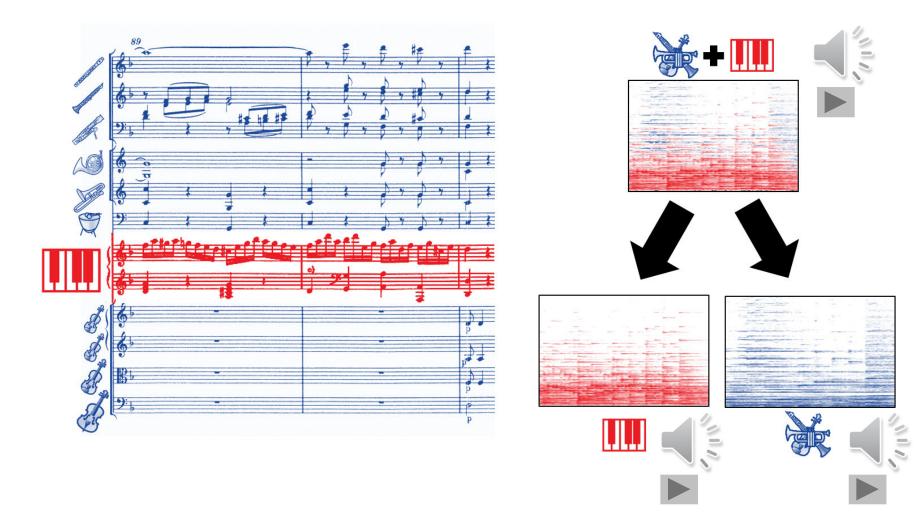




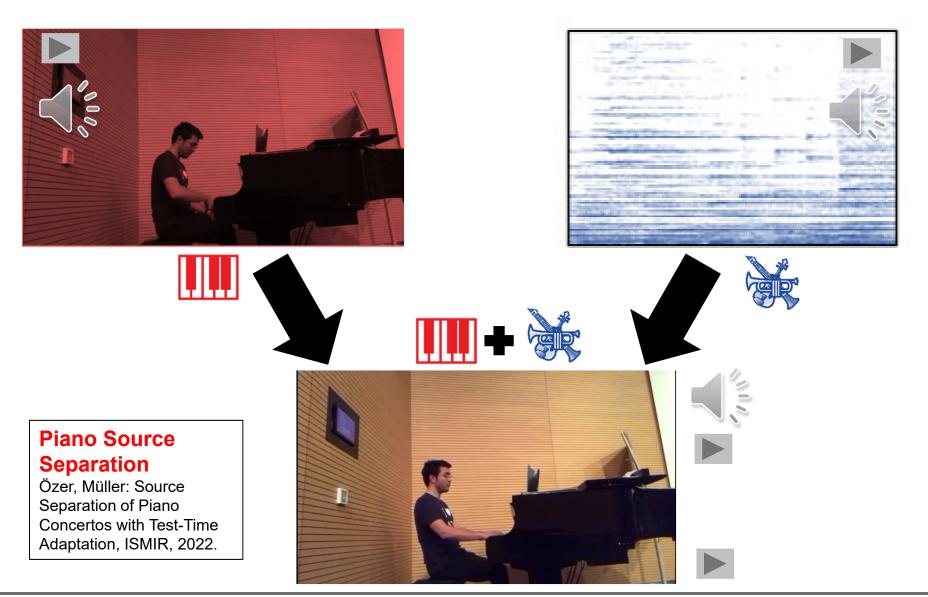














References (NMF, NAE)

- Daniel Lee and Sebastian Seung: Algorithms for Non-Negative Matrix Factorization. Proc. NIPS, 2000.
- Sebastian Ewert and Meinard Müller: Using Score-Informed Constraints for NMF-Based Source Separation. Proc. ICASSP, 2012.
- Paris Smaragdis and Shrikant Venkataramani: A Neural Network Alternative to Non-Negative Audio Models. Proc. ICASSP, 2017.
- Sebastian Ewert and Mark B. Sandler: Structured Dropout for Weak Label and Multi-Instance Learning and Its Application to Score-Informed Source Separation. Proc. ICASSP, 2017.
- Yigitcan Özer, Jonathan Hansen, Tim Zunner, and Meinard Müller: Investigating Nonnegative Autoencoders for Efficient Audio Decomposition. Proc. EUSIPCO, 2022.

